NHTSA Workshop – Nov 6, 2016

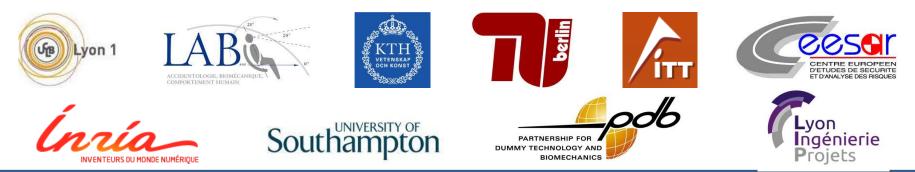


Development of an Open Source Framework to position and personalize Human Body Models

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Background and motivation

- Human Body Models: performance increasing ...
- **++** stable, approaching all known PMHS responses (better than dummies...),
- ++ a few families available
- -- same sizes as dummies
- -- Typically one posture only = daily use difficult (vehicle, research, OOP, precrash...)
- -- not always easy to access (does not help for specifications, reproducibility, procedures...)



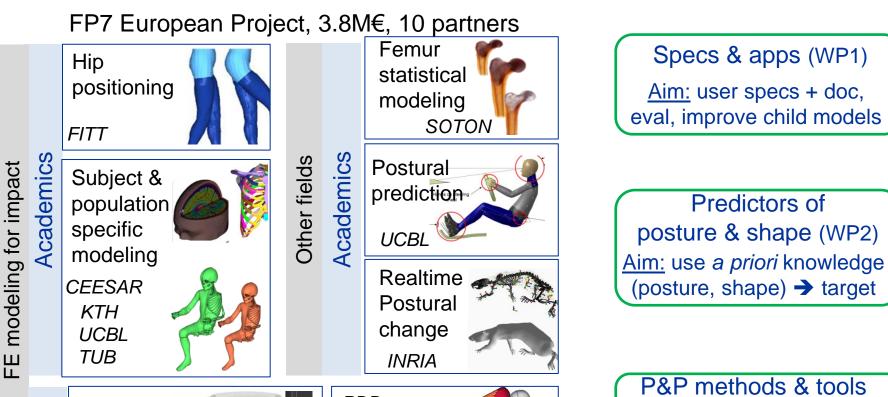
Thums (source: Toyota Newsroo





PIPER Project (Nov 2013 - Apr 2017)

Objectives: methods and tools position and personalize HBM
 Child model (PIPER child model, 1.5-6YO) → Open Source



(WP3)

Aim: transform HBM (num)

PDB

Partnership

Dummy Tech. and Biomech





PIPER software: A Modular Framework

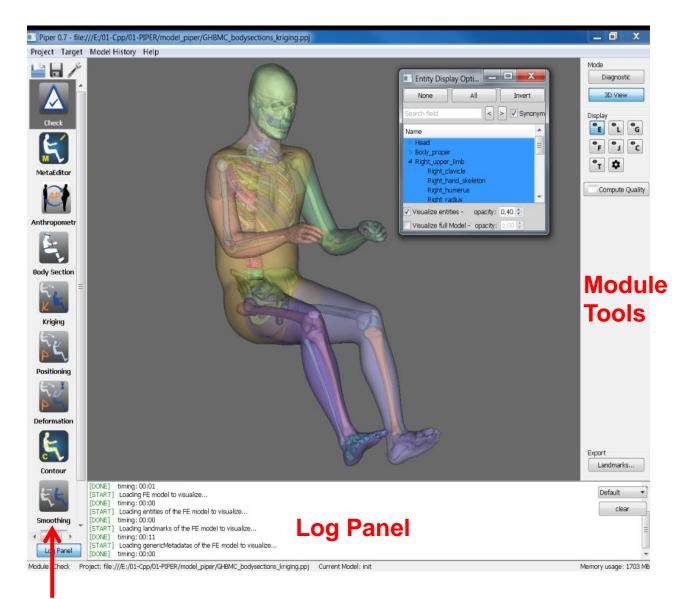
- FE HBM I/O
- Project Save/Open
- Modules that can update data (history/undo)
- Interactive GUI (+batch mode)
- Model visualization

Windows / Linux



TetGen, Mesquite

. . .

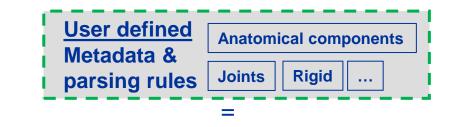


Module Selection



PIPER Framework: I/O - Import FE HBM



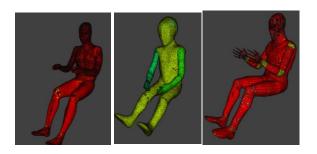


User:

+

defines FE groups using <u>standard preprocessing software</u> to describe anatomical entities, landmarks, contacts → FE Format
 associates groups and anatomical entities (AnatomyDB), joints, contacts → XML file
 selects rules to parse FE format input → XML File (provided, can be modified to add features or code)

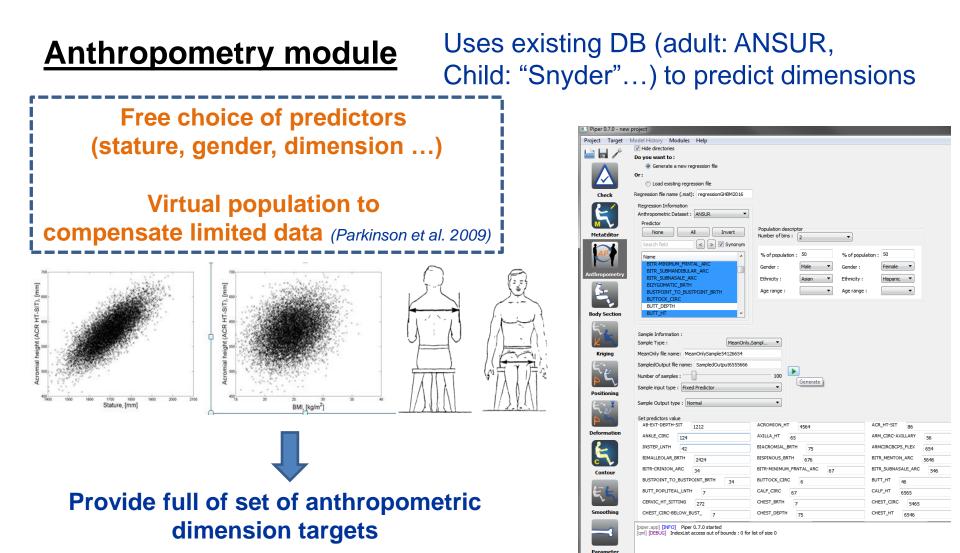
Used so far: GHBMC (Dyna/Pam), Thums, Piper Child model, (Viva)





Workflow example: scaling based on anthropometry

1 – Definition of target body dimensions: Anthropometry Module



Workflow example: PIPER scaling based on anthropometry

- 1 Definition of target body dimensions
- 2 Describe body dimensions on the HBM: Body Section Module

<u>Body</u> section module

- Link anthro to HBM dimensions
- Generates control points

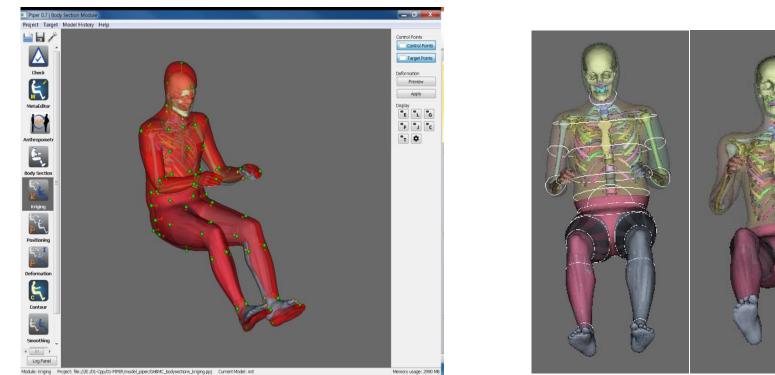
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Module: Check Project: file:///E:/01-Cpp/01-PIPER/model_piper/GHBMC_bodysections_kriging.ppj Current Model: init

Workflow example: Scaling based on anthropometry

- 1 Definition of target body dimensions
- 2 Describe body dimensions on the HBM
- 3 Deform the model: Kriging module
- 4 (optional) apply other modules (ex: change parameter defined in metadata such as material properties), post process (smoothing, ...)

Kriging module





Post processing tools

Mesh Quality Metrics:

Calculation and display incl. <u>relative</u> quality (between / after...)

Mesh Quality Optimizer:

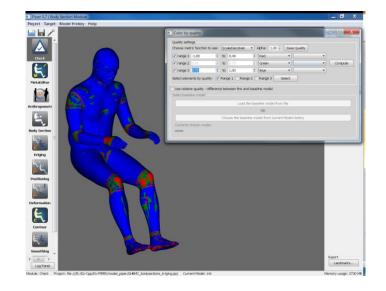
Optimize locally element quality (using MESQUITE Toolkit)

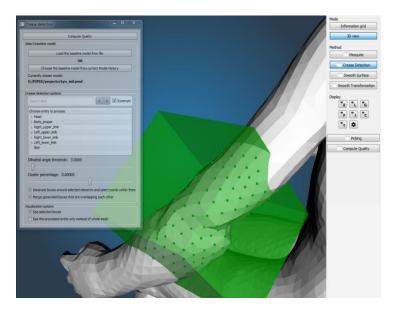
Transformation smoothing module:

Smooth (/edit) surface, regional smoother of transformation (between surface constraints)

Aims: maintain quality, (typically) respect contacts

Applicable to any workflow

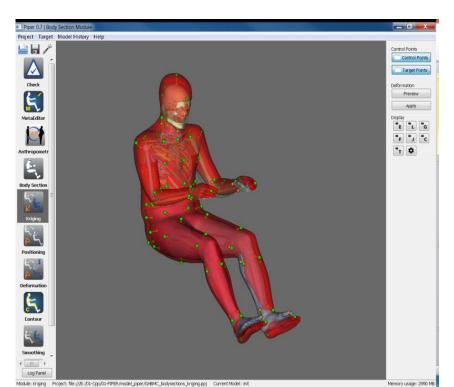




Workflow example: PIPER scaling based on anthropometry

- 1 Definition of target body dimensions
- 2 Describe body dimensions on the HBM
- 3 Deform the model
- 4 (optional) apply other modules (ex: smoothing, change parameter defined in metadata such as material properties) ...

5 – Export



Updated and Baseline FE models

Export





Summary/status: scaling / personalization

Based on anthropometry

- Modules available
 need to refine, integrate more workflows, etc...
 (e.g. length in body section, more skeletal constraints)
 - Methodology already defined and tested

• (ongoing) PIPER child model dedicated workflow

- Age vs. Anthro, local geom, some material (growth cartilage, brain)
- Note: use of external/user Octave/Matlab scripts possible...





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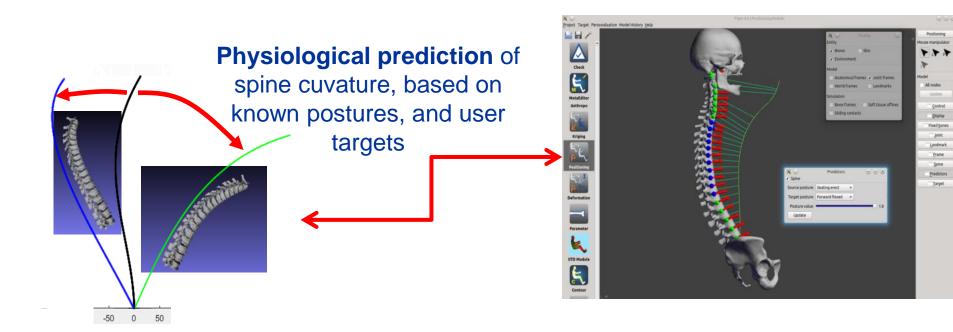
- Age vs. Anthro, local geom, some material (cartilage, brain)
- Note: use of external/user Octave/Matlab scripts possible...
- (Missing) Based on statistical Shape Models of full skeleton:
 - Still missing...but hoping to have it at the end...
- Other schemes are possible... but time is short





1 – Define the target position: Interactive Positioning Module

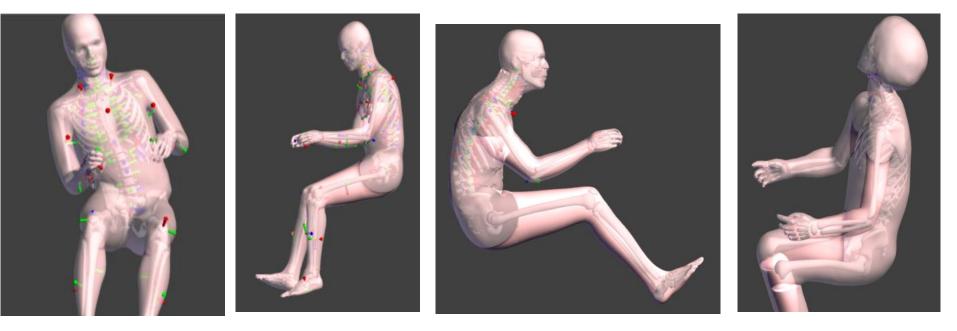
- <u>lightweight physics model</u> automatically create (HBM + Metadata).
- Includes functional constraints: bone collision, sliding contacts, joints...
- + User constraints: fixed bone, joint angle, bone landmark position...
- + A priori (biomech, ergo...) constraints to increase realism of target
- ➔ (real time) simulation to compute posture





1 – Define the target position: Interactive Positioning Module

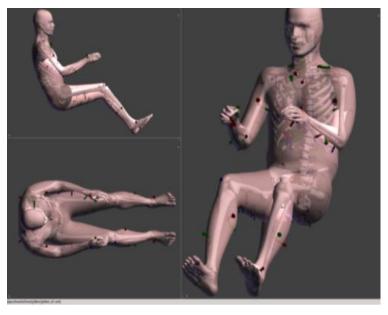
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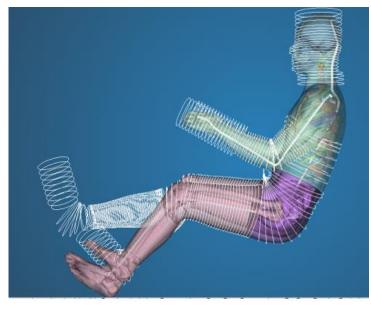


- 1 Define the target position
- 2 Deform the model: two approaches available inside PIPER
 - + possible to use simulation workflow (updated model or landmarks used as simulation target) → automation ongoing

Physics-based Transformation¹:



Contours-based Transformation²:



[1] B. Gilles, et al. Frame-based interactive simulation of complex deformable objects, 2013[2] D. Jani et al., Repositioning the knee joint in human body FE models using a graphics based technique, 2012.



- 1 Define the target position:
- 2 Deform the model
- 3 Improve regional mesh quality: smoothing
- 4 Update FE model





Before Positioning **After Positioning**



Summary/status: Positioning

- Applied to different models
- Fully successful (=directly runnable output model) on sagittal movement. Range of motion is of course an important parameter...
- Limitations: Still working on improving the lightweight physics simulation (soft contacts, transformation...), contours, debugging/robustness, a priori knowledge integration, integration with simulation workflow

Reminders:

- Large range of motion likely to affect mesh deformation/quality independently of the deformation method used
- HBM design can limit their usability for positioning (continuous mesh, lack of sliding component bones/soft tissues...)



Conclusions

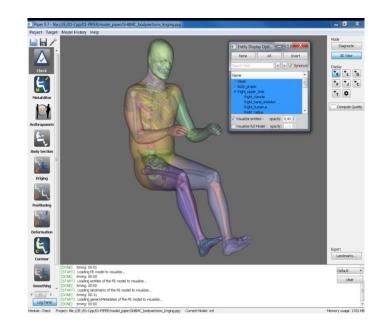
- Novel (unique) framework for P&P, using modular approach
 - FE code and model independent
 - Accounts for actual workflow (industries & acad users)
 - OPEN. Methods/data (yours?) can be added
- Beta version of software ready (import/export, modules...)
 - Workflows being developed / used for applications
- External beta testing: starting soon (short timeline, NDA)
 - Aim: gaps user expectation vs. functionalities, stability, priorities
- Perspectives
 - Add more modules (a priori, ...), bug fix, feedback ...
 - Public release: April 2017... (workshop in Paris). License:
 - Software: GPL v2 or later ;
 - Child model: GPLv3 + Open Science clause
 - Metadata: talks model providers
 - Open Source management structures: maintenance, ...



Thank you

Release: April 2017 Final Workshop in Paris





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Overall approach and project structure

